

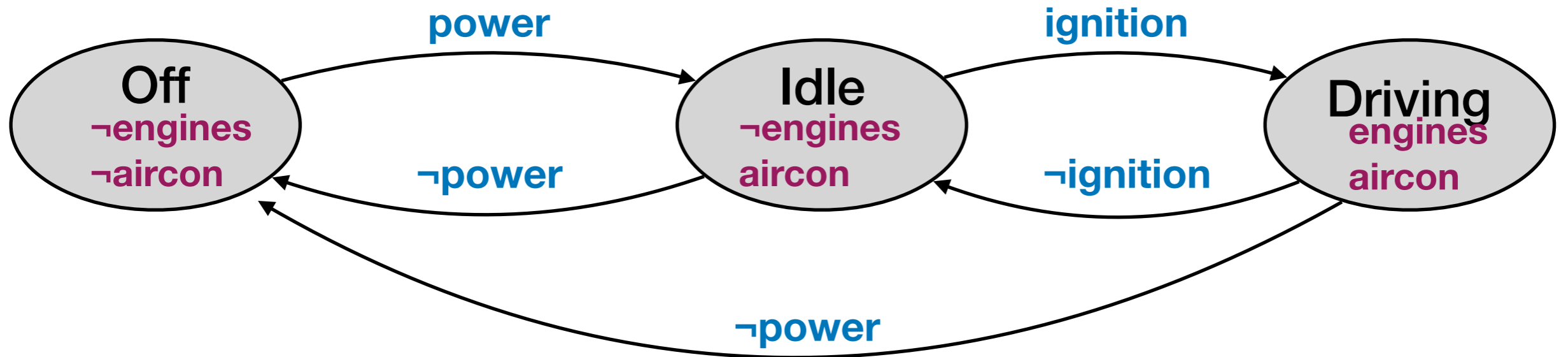


**Pretending to verify a
train controller
with Lustre**

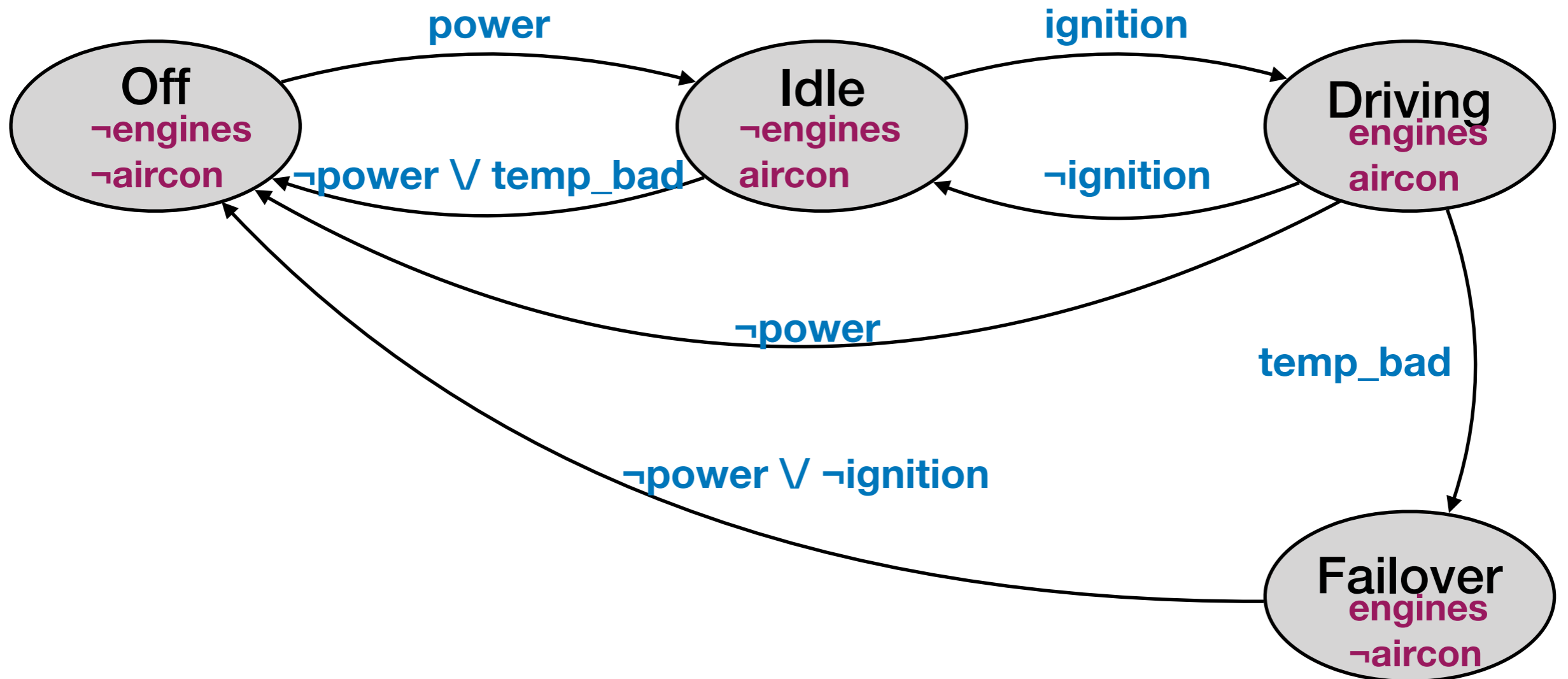
First, we need a pretend controller

- Controls the high level state machine
- Supervises the system

Simple controller



with failover mode



How do we implement this?

- Runs on microcontroller
- Limited space
- Can't have out-of-memory errors
- Predictable runtime

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- Runs on microcontroller => C (of course)
- Limited space => C (no runtime)
- Can't have out-of-memory errors => C (don't malloc)
- Predictable runtime => C (don't branch too much)

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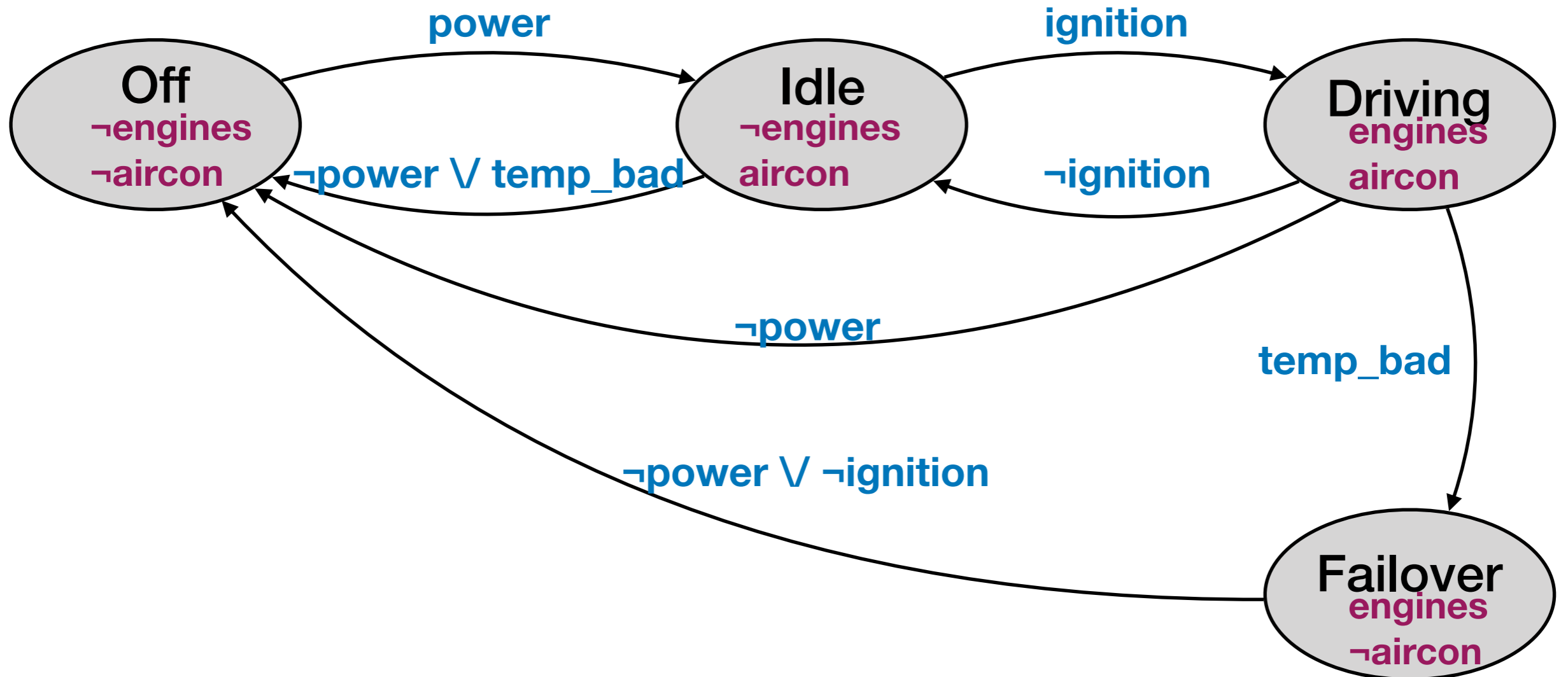
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- Limited space => C (no runtime)
- Can't have out-of-memory errors => C (don't malloc)
- Predictable runtime => C (don't branch too much)

```
switch (state) {
    case OFF:
        if (power()) {
            aircon_on();
            state = IDLE;
        }
        break;
    case IDLE:
        if (!power() || temp_bad()) {
            aircon_off();
            state = OFF;
        } else if (ignition()) {
            engines_on();
            state = DRIVING;
        }
        break;
    case DRIVING:
        if (!ignition()) {
            engines_off();
            state = IDLE;
        } else if (temp_bad()) {
            aircon_off();
            state = FAILOVER;
        }
        break;
    case FAILOVER:
        if (!power() || !ignition()) {
            engines_off();
            state = OFF;
        }
}
}
```


Bad

```
switch (state) {
  case OFF:
    if (power()) {
      aircon_on();
      state = IDLE;
    }
    break;
  case IDLE:
    if (!power() || temp_bad()) {
      aircon_off();
      state = OFF;
    } else if (ignition()) {
      engines_on();
      state = DRIVING;
    }
    break;
  case DRIVING: are the engines on or off in DRIVING state?
    if (!ignition()) {
      engines_off();
      state = IDLE;
    } else if (temp_bad()) {
      aircon_off();
      state = FAILOVER;
    }
    break;
  case FAILOVER:
    if (!power() || !ignition()) {
      engines_off();
      state = OFF;
    }
}
}
```

Beautiful



More beautiful

```
node controller(power, ignition, temp_bad : bool)  
    returns (engines, aircon : bool)
```

```
node controller(power, ignition, temp_bad : bool)
  returns (engines, aircon : bool)
let
  automaton
  initial state OFF
  unless
    if power restart IDLE
  end
  let (engines, aircon) = (false, false); tel

  state IDLE
  unless
    if not power or temp_bad restart OFF
    elsif ignition restart DRIVING
  end
  let (engines, aircon) = (false, true); tel

  state DRIVING
  unless
    if temp_bad restart FAILOVER
    elsif not ignition restart IDLE
    elsif not power restart OFF
  end
  let (engines, aircon) = (true, true); tel

  state FAILOVER
  unless
    if not power or not ignition restart OFF
  end
  let (engines, aircon) = (true, false); tel
tel
```

Good

```
node controller(power, ignition, temp_bad : bool)
  returns (engines, aircon : bool)
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  state IDLE
  unless
    if not power or temp_bad restart OFF
    elsif ignition restart DRIVING
  end
  let (engines, aircon) = (false, true); tel

  state DRIVING
  unless
    if temp_bad restart FAILOVER
    elsif not ignition restart IDLE
    elsif not power restart OFF
  end
  let (engines, aircon) = (true, true); tel
  better than C: clear that engines always on in DRIVING

  state FAILOVER
  unless
    if not power or not ignition restart OFF
  end
  let (engines, aircon) = (true, false); tel
tel
```

Good

```
node controller(power, ignition, temp_bad : bool)
  returns (engines, aircon : bool)
let
  automaton
  initial state OFF
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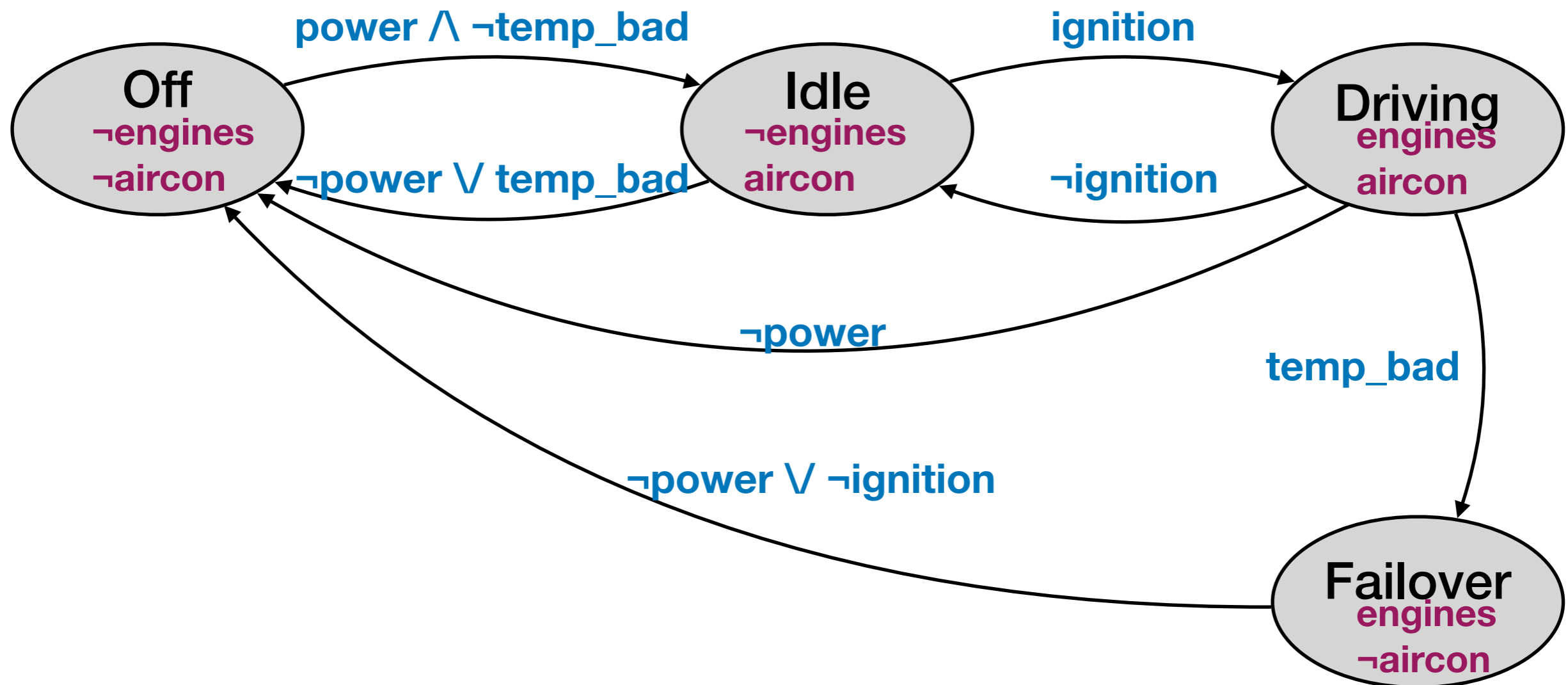
  state IDLE
  unless
    if not power or temp_bad restart OFF
    elsif ignition restart DRIVING
  end
  let (engines, aircon) = (false, true); tel

  state DRIVING
  unless better than diagram: unambiguous transition precedence
    if temp_bad restart FAILOVER
    elsif not ignition restart IDLE
    elsif not power restart OFF
  end
  let (engines, aircon) = (true, true); tel
  better than C: clear that engines always on in DRIVING
  state FAILOVER
  unless
    if not power or not ignition restart OFF
  end
  let (engines, aircon) = (true, false); tel
tel
```

Workflow

- Write Lustre
- Verify Lustre implementation of FSM
- Compile to C
- Integrate generated C with rest of system

A property we might want:
“if temp is bad, air con is off”



Checking properties with Kind2

```
node controller(power, ignition, temp_bad : bool)
    returns (engines, aircon : bool)
let
    --%PROPERTY temp_bad => not aircon;
```

Checking properties with Kind2

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```

<Failure> Property (temp_bad => (not aircon)) is invalid by bounded model checking for k=0 after 0.070s.

Counterexample:

```
Node controller ()
  == Inputs ==
  power      true
  ignition   false
  temp_bad   true
  == Outputs ==
  aircon     true
  == Automaton automaton1 ==
  state      IDLE
  restart    true
```

Fix is easy...

```
node controller(power, ignition, temp_bad : bool)
  returns (engines, aircon : bool)
let
  --%PROPERTY temp_bad => not aircon;
  automaton
  initial state OFF
  unless
    if power restart IDLE
  end
  let (engines, aircon) = (false, false); tel
```

Fix is easy...

```
node controller(power, ignition, temp_bad : bool)
  returns (engines, aircon : bool)
let
  --%PROPERTY temp_bad => not aircon;
  automaton
  initial state OFF
  unless
    if power and not temp_bad      restart IDLE
  end
  let (engines, aircon) = (false, false); tel
```

Success!

```
node controller(power, ignition, temp_bad : bool)
  returns (engines, aircon : bool)
let
  --%PROPERTY temp_bad => not aircon;
  automaton
  initial state OFF
  unless
    if power and not temp_bad      restart IDLE
  end
  let (engines, aircon) = (false, false); tel
```

Summary of properties:

(temp_bad => (not aircon)): valid (at 1)
=====

Conclusion

- It's a simple idea, but it fills a niche that I don't know of any other solutions for.
- I think Lustre is a language that really nails the “less expressive is better” as it allows strong reasoning about embedded code